

DATA ACQUISITION SYSTEM FOR NONDESTRUCTIVE EVALUATION OF SPENT NUCLEAR FUEL

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INEEL

Introduction

- Need to inspect Spent Nuclear Fuel canisters
- Spent Fuel must be removed from wet storage by 2003
- Inspection system assists in this move

Multi-Axis Inspection System



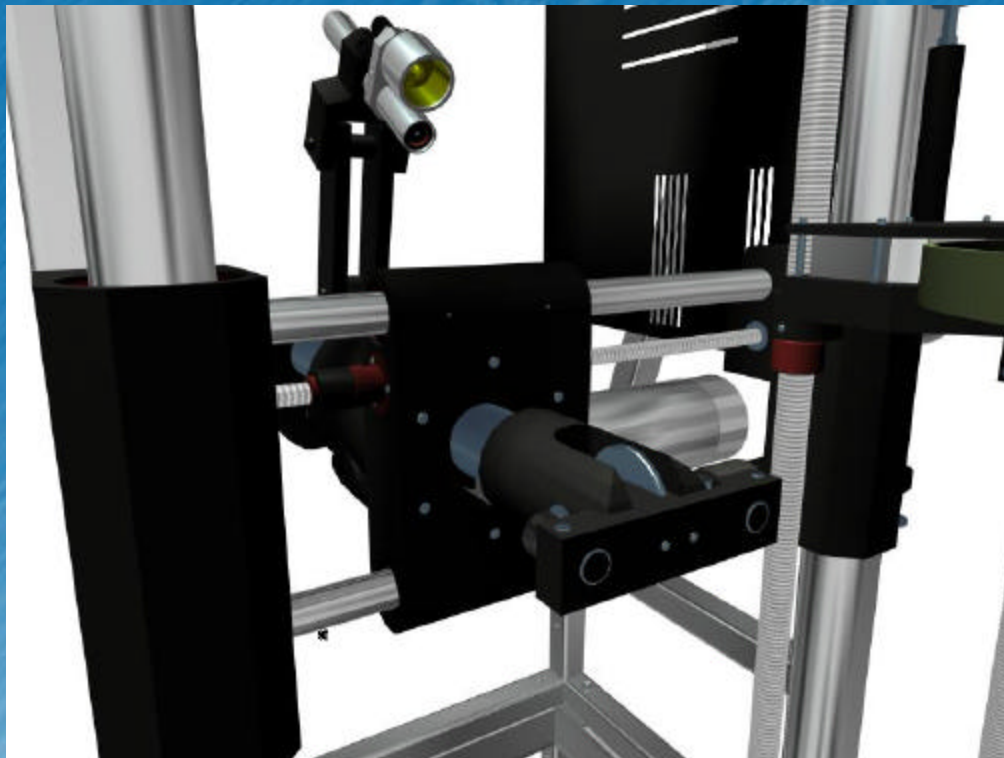
- 10 axes of motion
(x,y,z,swivel, gimbal)*2
- Ultrasonic tests
- Video navigation
- Remotely operated
- Scanner is submerged

Two Major Components



- Control console
- Remote scanner

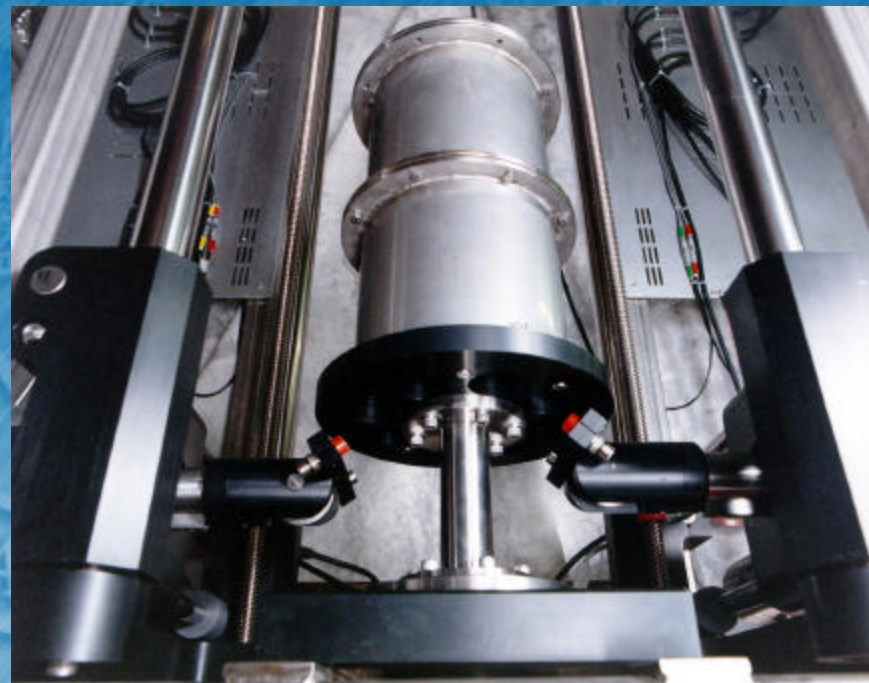
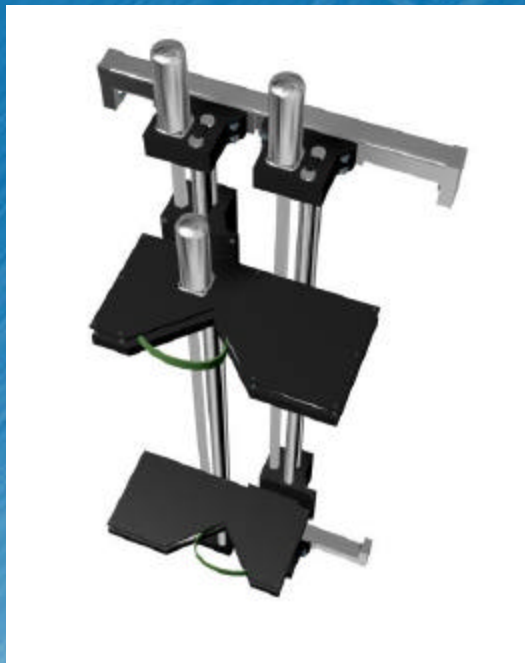
Sensors



- Four ultrasonic transducers
- Three video cameras

Options

- 'V-clamp'
- Turntable



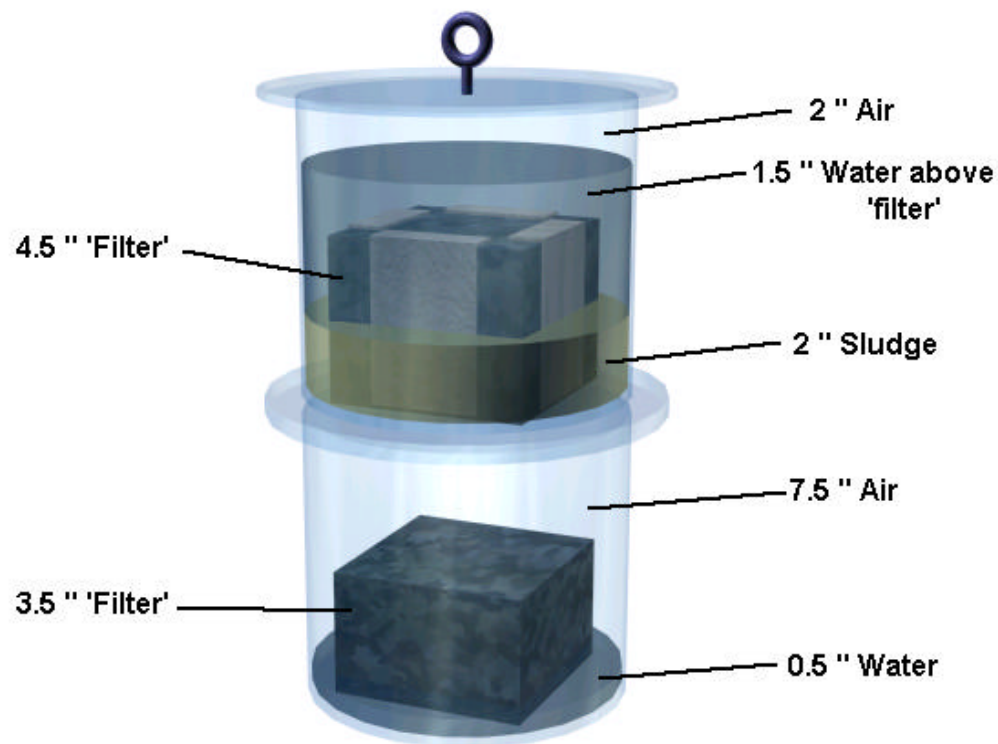
System Capabilities

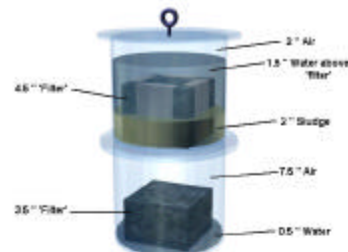
- Detect water intrusion
- Detect and quantify corrosion in canister walls
- Image canister contents
- Determine or verify canister dimensions

Mechanical Performance

- X (front-to-back) 9.2" $\pm 0.005"$
- Y (in-out) 9.0" $\pm 0.005"$
- Z (vertical) 61.3" $\pm 0.005"$
- Gimbal (xducer angle) 150° 1°
- Swivel (xducer rotation) 349° 1°

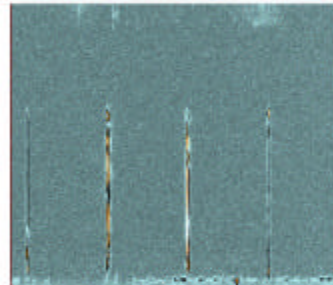
Reference Standards





Reference Standard

Sample Data



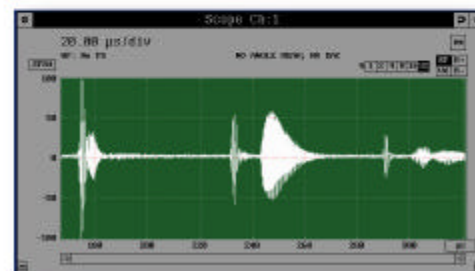
Internal Reflectors



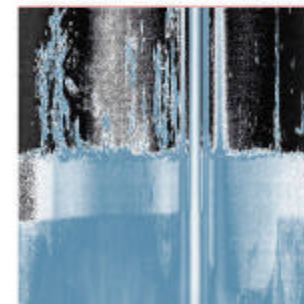
Ring-Down



Thru-Transmission



Up-Looking (A-scan)

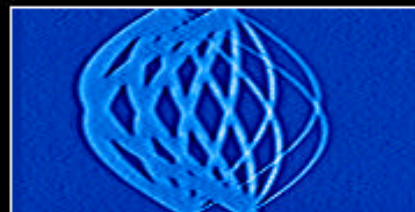


Ring-Down w/ Sludge

Future - Tomographic Imaging



SINOGRAM



FILTERED SINOGRAM

FILE: R25M03.CS1
25 MHz Xducers

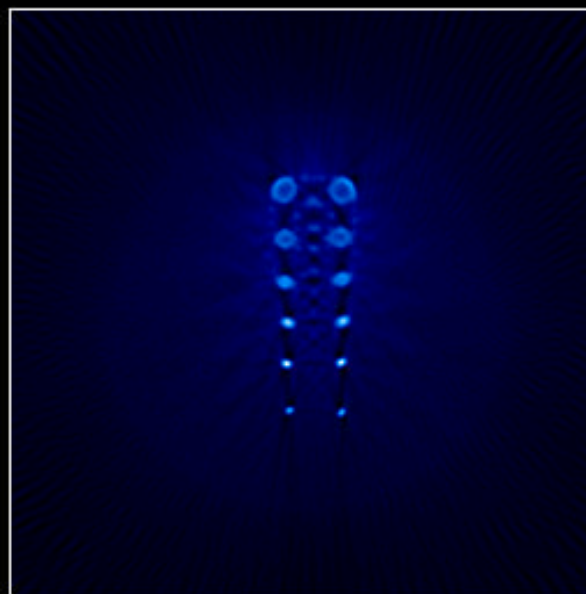
Aperture width: 180
Sinogram Offset: -4

Number of views: 90

Filter: Gen_Hamming
Kernel Size: 5

STRAIGHT-RAY,
TRANSMISSIVE
TOMOGRAPHY

INEEL NDE Physics
Thu, Jul 30, 1998



RECONSTRUCTION